

Minimizing I/Os in Out-of-Core Task Tree Scheduling

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Scientific application workflows

- ▶ Described as DAGs: nodes = tasks, edges = dependencies
- ▶ Can be a **tree** (multifrontal sparse matrix factorization)

Focus on the memory needs

- ▶ Larger memory footprint: may not fit in main memory
- ▶ Resort to storing some files on disk: **out-of-core** execution
- ▶ Expensive disk access delays the execution
- ▶ Scheduling choices impact memory usage

Objective: **Minimize I/Os while scheduling a tree-shaped workflow**

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Ultimate goal: [parallel processing](#)

- ▶ Problem: sequential case not well understood yet
- ▶ Our contribution: step towards its understanding

Task tree

- ▶ Tree $G = (V, E)$, each node has a single parent, $|V| = n$
- ▶ Output file of a node i : size w_i (integer number of slots)
- ▶ A node must be executed after all its children

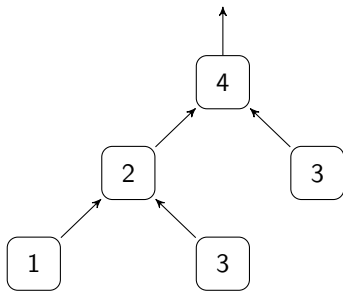
Memory model

- ▶ Main memory of size M , infinite disk
- ▶ Can move a slot to disk at unit cost: 1 I/O

Memory Management when a node is executed

- ▶ Children' output files stored in main memory
- ▶ Directly replaced by the node's output file (never coexist)

Example, $M = 5$

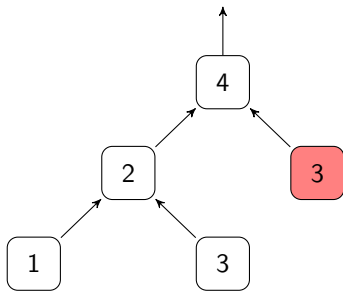


Memory: 0 / 5

Disk: 0

I/Os: 0

Example, $M = 5$

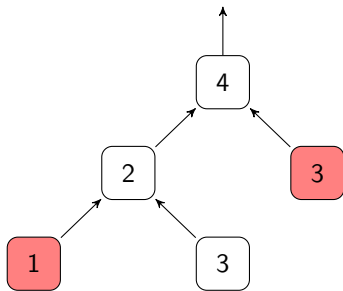


Memory: 3 / 5

Disk: 0

I/Os: 0

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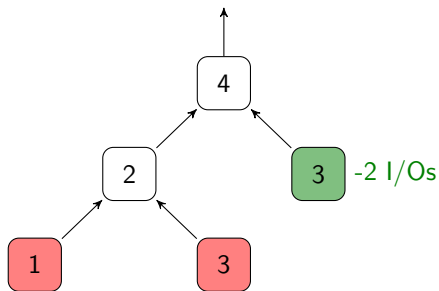


Memory: 4 / 5

Disk: 0

I/Os: 0

Example, $M = 5$

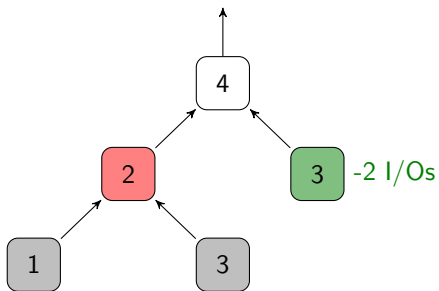


Memory: 5 / 5

Disk: 2

I/Os: 2

Example, $M = 5$

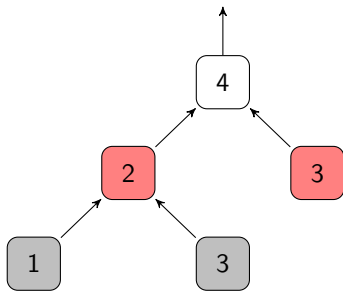


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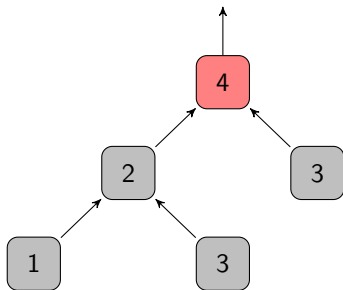


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Example, $M = 5$



Memory: 4 / 5

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Other models used in the literature

- ▶ Input and output files coexist
- ▶ Additional memory used during execution
- ▶ Describe more accurately the reality

Advantages of this model [Liu 1986, 1987]

- ▶ Simpler theoretic study
- ▶ Previous models can be simulated by this one

Traversal

- ▶ **Schedule** σ : $\sigma(i) = t$ if task i is the t -th executed
- ▶ **I/O function** τ : output file of task i has $\tau(i)$ slots written to disk
- ▶ Assume wlog that the data is written to disk ASAP and read ALAP

Validity of a traversal

- ▶ Schedule respects precedences
- ▶ I/Os consistent: $\tau(i) \leq w_i$
- ▶ The main memory (size M) is never exceeded, $\forall i \in V$:

$$\left(\sum_{\substack{(k,p) \in E \\ \sigma(k) < \sigma(i) < \sigma(p)}} (w_k - \tau(k)) \right) + \max \left(w_i, \sum_{(j,i) \in E} w_j \right) \leq M$$

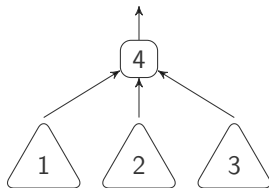
The MINIO problem

Given a tree G and a memory limit M , find a valid traversal that minimizes the total amount of I/Os ($= \sum \tau(i)$).

Lemma: knowing the optimal σ or τ is enough

An interesting subclass: postorder traversals

- ▶ Fully process a subtree before starting a new one
- ▶ Completely characterized by the execution order of subtrees
- ▶ Widely used in sparse matrix softwares (e.g., MUMPS, QR-MUMPS)



Peak memory minimization [Liu 1986, 1987]

- ▶ Optimal Postorder algorithm: `POSTORDERMINMEM` in $\mathcal{O}(n \log n)$
- ▶ Optimal algorithm `MINMEMALGO` in $\mathcal{O}(n^2)$

Minimizing I/Os without splitting files [Jacquelin et al. 2011]

- ▶ Implies combinatorial choices: NP-complete
- ▶ NP-complete even restricted to postorders, or with σ known

Model similar to ours [Agullo et al. 2010]

- ▶ Optimal Postorder algorithm `POSTORDERMINIO` in $\mathcal{O}(n \log n)$
- ▶ Did not consider the general problem

Theorem

Both POSTORDERMINMEM and POSTORDERMINIO minimize I/Os on homogeneous trees (unit file sizes).

Note: POSTORDERMINMEM does not rely on M so is optimal for any memory size and several memory layers (cache-oblivious)

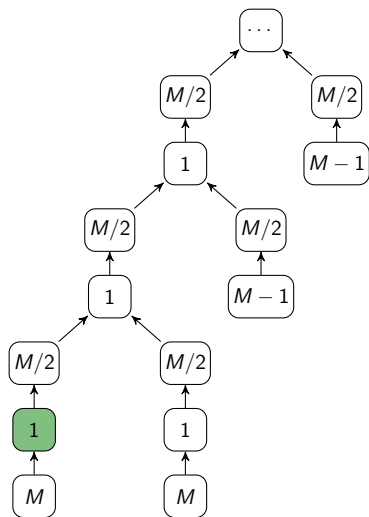
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But POSTORDERMINIO is **not competitive** on heterogeneous trees...

POSTORDERMINIO is not competitive



I/O optimal

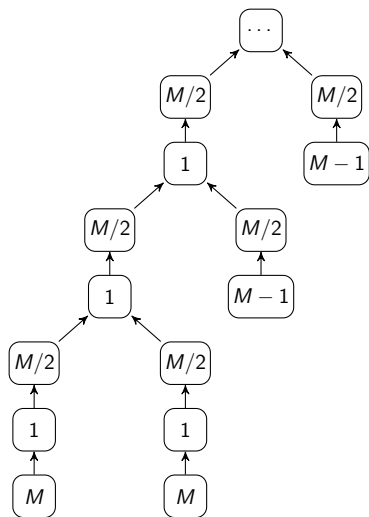
- ▶ Peak memory: $M + 1$
- ▶ I/Os: 1

POSTORDERMINIO

- ▶ Peak memory: $\frac{3}{2}M$
- ▶ I/Os: $\Theta(|V|M)$

Competitive ratio: $\Omega(|V|M)$

POSTORDERMINIO is not competitive



I/O optimal

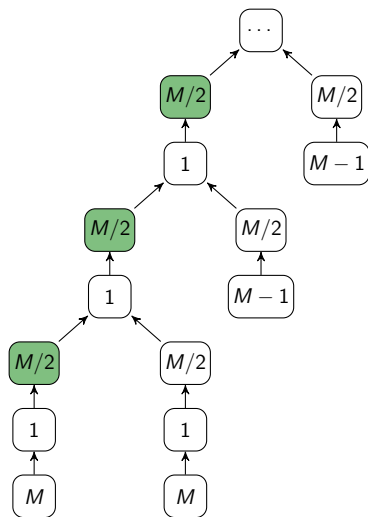
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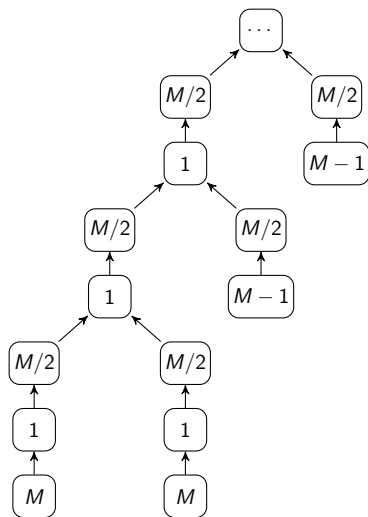
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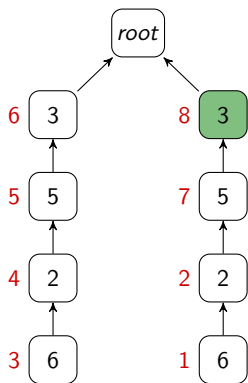
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Can we rely on MINMEMALGO?

MINMEMALGO is not competitive

$M = 6$



I/O Optimal

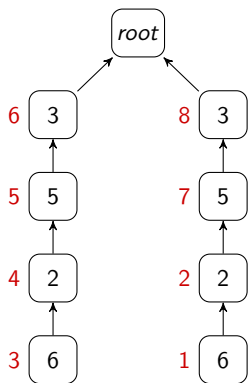
- ▶ Peak memory: 9
- ▶ I/Os: 3

MINMEMALGO (red labels)

- ▶ Peak memory: 8
- ▶ I/Os: 4

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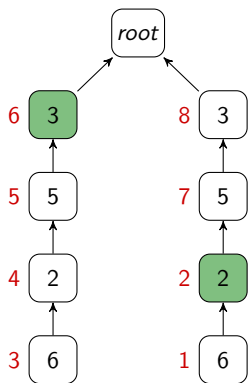
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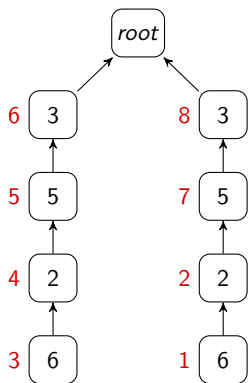
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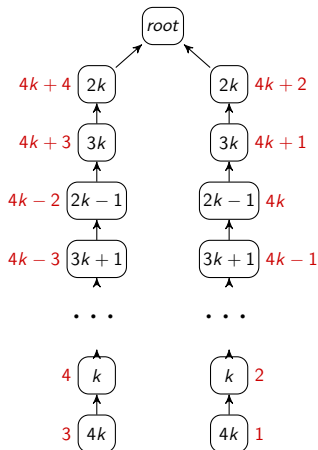
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I/O Optimal

- ▶ Peak memory: $6k$
- ▶ I/Os: $2k$

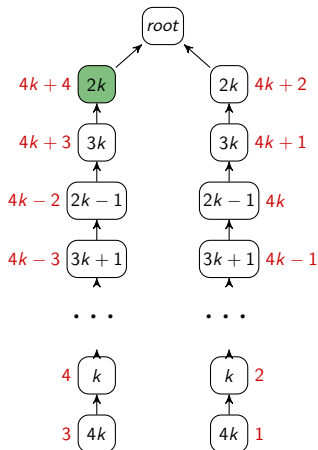
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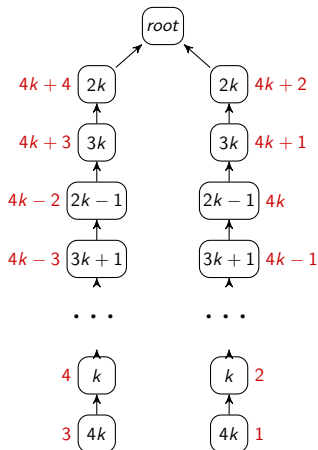
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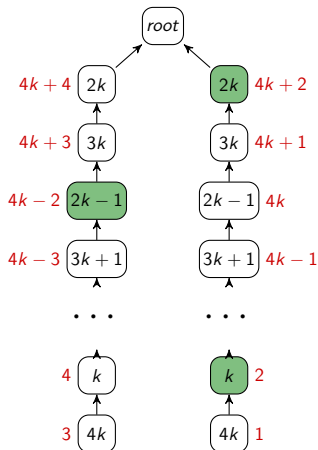
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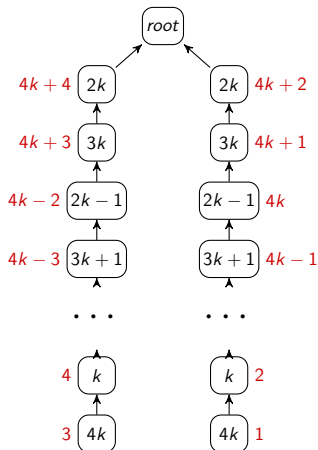
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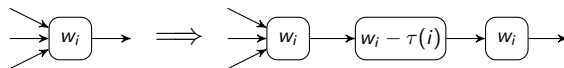
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Existing solutions not satisfactory: need for a new heuristic

New heuristic: FULLRECEXPAND

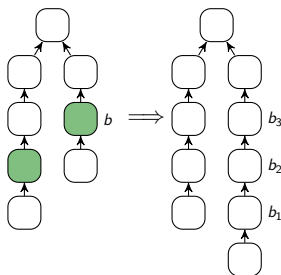
General description

- ▶ Underlying concept: run MINMEMALGO several times
- ▶ Each run: identify an I/O, then enforce it in the graph



FULLRECEXPAND

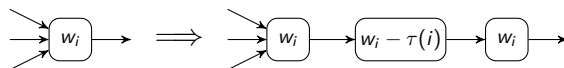
- ▶ Recursive calls on the root's children
- ▶ While MINMEMALGO needs I/Os:
 - Enforce the I/O that is the latest to be read from disk



New heuristic: FULLRECEXPAND

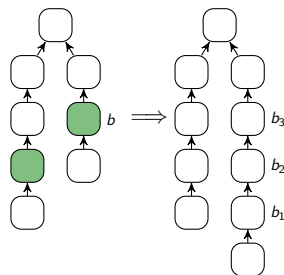
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RECEXPAND ($\mathcal{O}(n^3)$): ≤ 2 iterations

Two datasets

- ▶ SYNTH: 330 synthetic binary trees of 3000 nodes uniformly drawn, memory weight uniform in $[1; 100]$
- ▶ TREES: 330 elimination trees of actual sparse matrices from 2000 to 40000 nodes (University of Florida Sparse Matrix Collection)
- ▶ Main memory size (M): mean of
 - Minimum memory for which a solution exists
 - Maximum memory for which I/Os are needed

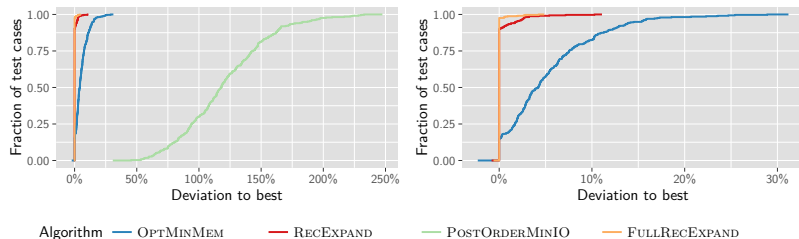
Heuristics

- ▶ MINMEMALGO, RECEXPAND, POSTORDERMINIO, FULLRECEXPAND

Performance

- ▶ If k I/Os are performed, performance is $1 + \frac{k}{M}$
- ▶ Objective: take into account the size of the main memory

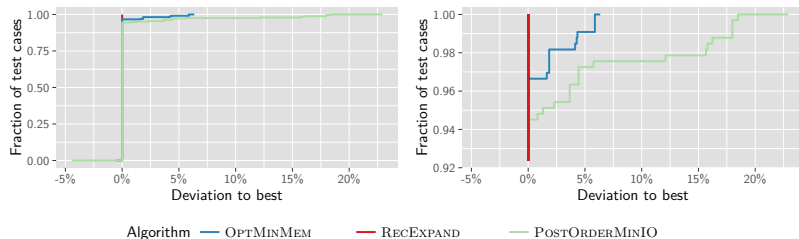
Results on SYNTH (right graph: zoom)



Analysis (*Performance profiles: best is top-left*)

- ▶ Left: POSTORDERMINIO performs poorly ($> 100\%$ deviation in 3/4 of the cases)
- ▶ Right: RECEXPAND significantly better than MINMEMALGO:
 - RECEXPAND best in $\approx 90\%$ of the cases
 - MINMEMALGO best in $\approx 13\%$ of the cases
- ▶ RECEXPAND is comparable to FULLRECEXPAND

Results on TREES (right graph: zoom)



Analysis (*best is top-left*)

- ▶ Smaller differences (right graph: zoom of the top-left part)
- ▶ Most of the graphs have “easy” solutions (cannot ensure optimality)
- ▶ REEXPAND is always the best heuristic
- ▶ MINMEMALGO outperforms POSTORDERMINIO

The MINIO problem

- ▶ Complexity still open, conjectured NP-hard
- ▶ Finding σ or τ suffices

Optimal solutions on subclasses

- ▶ Optimal postorder algorithm was already known
- ▶ POSTORDERMINMEM optimal for homogeneous trees

Heuristics

- ▶ MINMEMALGO performances are not bad
- ▶ REEXPAND successfully combines the concepts of MINMEMALGO and the memory limit

Perspectives

- ▶ Recall: only concerns sequential schedules
- ▶ Next step: study I/O efficient parallel schedules (e.g., via memory booking)